

#### 4. Conclusiones

Hemos mostrado cómo el proceso de integración numérica de las ecuaciones de movimiento puede introducir en las ecuaciones de condición perturbaciones que pueden ser pequeñas pero no despreciables. Estas perturbaciones a su vez pueden amplificarse considerablemente en el proceso de corrección diferencial. Consideramos que ésta es una explicación plausible para las anomalías que se presentan en el cálculo de aquellos cometas que registran pasos muy próximos al Sol o a algún planeta. Las conclusiones que se obtengan acerca de las fuerzas no gravitatorias que actúan sobre los cometas no pueden considerarse como definitivas si no se ha hecho un análisis de los errores sistemáticos de cálculo para eliminarlos o al menos obtener una estimación correcta de ellos.

Nos proponemos realizar en el próximo futuro una serie sistemática de experimentos numéricos con órbitas y modelos de cometas típicos aplicando las técnicas resumidas en el presente informe.

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- (2) Marsden, B. G., A. J. 74, 1969.
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- (8) Zadunaisky, P. E., Proc. I.A.U. Symp. N° 25, 1964.
- (9) Zadunaisky, P. E., Proc. Symp. on "Periodic Orbits Resonance and Stability", S. Paulo, Brasil, 1969 (Reidel Publ. Co.).
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it is easily seen from triangles  $STP_1$  and  $STP_2$  that:

$$P_2T - P_1T = \frac{r_2^2 - r_1^2}{\Delta}$$

from which we obtain:

$$\frac{1}{\Delta} = \frac{1}{r_2^2} \frac{P_2T - P_1T}{1 - \frac{r_1^2}{r_2^2}}$$

It is evident that:

$$P_1T = r_1 \sin \theta_1, \quad P_2T = r_2 \sin \theta_2$$

2. — In order to put angles  $\theta_1$  and  $\theta_2$  in terms of orbital elements, let us take the projections of the orbits on the celestial sphere (fig. 3).

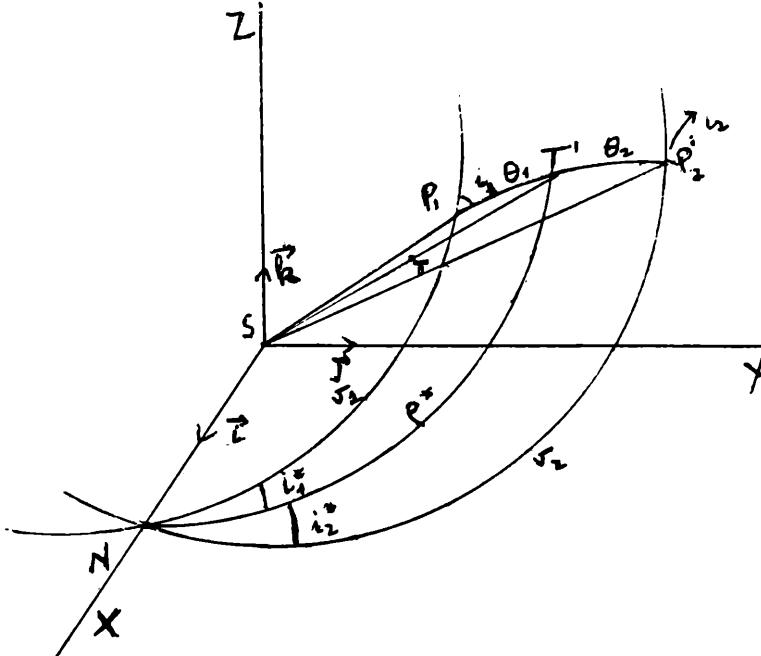


Fig. 3 — The set XYZ is centered in the Sun, the X axis being nodal line of the orbital planes of  $P_1$  and  $P_2$ .

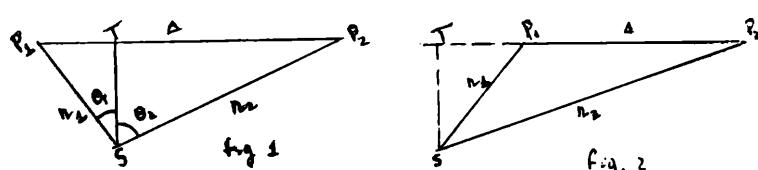
#### On a new form the main part of the disturbing function in the three-body problem

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**Abstract:** A new form for the disturbing function is given in terms of the heliocentric distances  $r_1$  and  $r_2$  and two auxiliary angles  $\theta_1$  and  $\theta_2$ . An outline is given for obtaining expressions of these angles in terms of known quantities.

1. — Let be given three point masses  $m_0(S)$ , the Sun,  $m_1(P_1)$  and  $m_2(P_2)$  the planets. Let  $r_1$  and  $r_2 > r_1$ , be the heliocentric distances of  $P_1$  and  $P_2$ . Writing  $\Delta$  for the mutual distance  $P_1P_2$ , and taking in figs. 1 and 2 ST perpendicular to  $P_1P_2$



Figs. 1 and 2 show two possible configurations of the three-body problem, excluded the collinear case.

Let  $T'$  be the projection of  $T$  on the Celestial Sphere. We shall consider the great circle passing through  $N$  and  $T'$ , upon which the auxiliary quantity  $\varphi^*$  will be computed. We indicate with  $i_1^*$  and  $i_2^*$  resp. the variable angles between the great circle and the orbital planes of  $P_1$  and  $P_2$ ;  $i_1$  and  $i_2$  are resp. the inclinations of the moving plane  $SP_1P_2$  with respect to these same planes. We suppose that approximate values of the orbital elements of both planets are known. Then, variable quantities can be determined in a first approximation by means of keplerian elements of  $P_1$  and  $P_2$ .

From spherical triangles  $T'NP'_1$  and  $T'NP'_2$  we get:

- 1) a)  $\cos \theta_1 = \cos v_1 \cos \varphi^* + \sin v_1 \sin \varphi^* \cos i_1^*$   
b)  $\cos \theta_2 = \cos v_2 \cos \varphi^* + \sin v_2 \sin \varphi^* \cos i_2^*$
- 2) a)  $\sin i_1^* \sin \varphi^* = \sin i_1 \sin \theta_1$   
b)  $\sin i_2^* \sin \varphi^* = \sin i_2 \sin \theta_2$
- 3) a)  $\sin \varphi^* \cos i_1^* = \cos \theta_1 \sin v_1 - \sin \theta_1 \cos v_1 \cos (180^\circ - i_1)$   
b)  $\sin \varphi^* \cos i_2^* = \cos \theta_2 \sin v_2 - \sin \theta_2 \cos v_2 \cos (180^\circ - i_2)$

Angles  $\theta_1$  and  $\theta_2$  must be expressed in terms of known approximate quantities. We first observe that:

$$\vec{SN} = \vec{X} \vec{i}, \quad \vec{ST} = \xi \vec{i} + \eta \vec{j} + \varsigma \vec{k}$$

$$\cos \varrho^* = \frac{\xi}{|\vec{ST}|}, \quad \sin \varrho^* = \frac{\sqrt{\eta^2 + \varsigma^2}}{|\vec{ST}|}$$

where:

$$a = \sqrt{\eta^2 + \varsigma^2}$$

The components  $\xi, \eta, \varsigma$  can be got, for instance, in the following form:

$$\begin{aligned}\xi - x_1 &= \lambda (x_2 - \xi) \\ \eta - y_1 &= \lambda (y_2 - \eta) \\ \varsigma - z_1 &= \lambda (z_2 - \varsigma)\end{aligned}$$

$\lambda$  is a variable parameter depending on the relationship between  $P_1 T$  and  $P_2 T$ .  $\lambda$  is such that:

$$\lambda = \frac{|P_1 T|}{|P_2 T|} = \frac{r_1 (r_1 - r_2 \cos H)}{\left( r_2^2 - 1 - \frac{r_1}{r_2} \cos H \right)}$$

(fig. 1) where  $H = \angle(r_1, r_2)$

Formulae 2a,b, and 3a,b give

$$\operatorname{tg} i_j^* = \frac{\sin \theta_j \sin i_j}{\cos \theta_j \sin v_j + \sin \theta_j \cos v_j \cos i_j}, \quad (j = 1, 2)$$

Inclinations  $i_1^*, i_2^*$ ,  $i_1$  and  $i_2$  are small in general. Time series of the form

$$4) \quad i = i^{(0)} + i^{(1)} + i^{(2)} + \dots, \quad (i = i_1, i_2, i_1^*, i_2^*)$$

can be ordinarily obtained from Taylor's expansions.

Formulae 1a,b can be solved by putting in a first approximation  $i_1^* = i_2^* = 0$ . Once the  $i^*$ 's have been computed from formulae (4) new values of  $\theta_1$  and  $\theta_2$  can be got.

These results can be improved after the integration of the corresponding sets of differential equations.